## YOKOGAWA

## TC10 操作手冊

## 操作說明：

## （一）SP 值設定：


（二）硬體參數設定：長按 ل鍵，顯示PASS 後，輸入 300 ，按下 】碓認。

## 1．設定輸入類型及控制模式 $\operatorname{Cod} 1$ ：




2．設定警報模式及服務功能 $\operatorname{Cod} 2$ ：


## 3．保存設定 ：



設定完成後會顯示此畫面，若要保存設定，只要按下 】 鍵即可。

若不想保存，則按 $?$ 鍵返回。

## （三）參數設定：長按 】鍵，顯示 PASS 後，輸入 20 ，按下】確認。

※操作過程中，按 可返回上一個參數

| 参數 | 内容 | 設定範圍 | 初始值 | 備註 |
| :---: | :---: | :---: | :---: | :---: |
| aPEr | 操作模式選挥 | $\begin{aligned} & \text { auto }=\text { 自動 } \\ & \text { oplo }=\text { 手哑 } \\ & \text { st.by }=\text { 待機 } \end{aligned}$ |  |  |
| 7．5P | 設定點選擇 | $0=$ SP， $1=$ SP2， $2=$ SP3， $3=$ SP4 | $0=\mathrm{SP}$ |  |
| tume | 自哑演算 | OFF＝關閉，ON＝啟䅉 | OFF | evoTUNE |
| Pb | 此例帯 | 1～9999（工業單位＝E．U．） | 50 | Eod 1 N值 $=1$ |
| E， | 稓分時間 | OFF（0）～ 9999 秒 | 200 |  |
| td | 微分時間 | OFF（0）～ 9999 秒 | 50 |  |
| H5EE | 釜滯ON／OFF控制 | 0～9999（E．U．） | 1 | Eod／N值 $=0$ |
| tc．H | 加熱輸出循環時間 | $0.1 \sim 130$ 秒 | 20.0 | ᄃod／N值 $=1$ |
| reb | 相噛冷卻增益 | 0．01～99．99 | 1.00 | $\begin{array}{\|l\|l\|} \hline \text { Cod } & \text { N值 }=1 \\ \text { Cod } 1 & \text { O值 }>4 \\ \hline \end{array}$ |
| tre | 冷卻輸出循環時間 | $0.1 \sim 130$ 秒 | 20.0 | $\begin{array}{\|l\|l\|} \hline \operatorname{Cod} & \text { N值 }=1 \\ \operatorname{Lod} & \text { O值 }>1 \\ \hline \end{array}$ |
| $5 P$ | 目標設定値1 | －1999～＋9999（E．U．） |  |  |
| 5 P | 目標設定値2 | －1999～＋9999（E．U．） |  | n5P＞1時 |
| 5 P3 | 目標設定値3 |  |  | －5P＞2 時 |
| 5 54 | 目標設定値4 |  |  | －5P＞3 時 |
| 5PLi | 目標設定檤下限 | －1999～SPHL（E．U．） |  |  |
| 5 PHL | 目標設定檤上限 | SPLL～ 9999 （E．U．） |  |  |
| n5P | 目標設定値數量 | 1～4 | 1 |  |
| RL I | 䛗斏1設定値 | AL1L $\sim$ AL1H |  | $\begin{aligned} & \text { 〔od2的P值 } \\ & >1 \text { 時 } \end{aligned}$ |
| RiL IL | 警報1下限設定値 | －1999～＋9999（E．U．） | －1999 |  |
| RL IH | 警斏1上限設定値 |  | 9999 |  |
| HRL 1 | AL1遅滯 | 1～9999（E．U．） | 1 |  |
| RLL 2 | 警報2設定値 | AL2L $\sim$ AL2H |  | $\begin{aligned} & \operatorname{Cod} 2 \text { 的 } \mathrm{Q} \text { 值 } \\ & >1 \text { 時 } \end{aligned}$ |
| RL $2:$ | 警報2下限設定値 | －1999～＋9999（E．U．） | －1999 |  |
| RLC CH | 知報2上限設定値 |  | 9999 |  |
| HR： 2 |  | $1 \sim 9999$（E．U．） | 1 |  |
| RL 3 | 警報3設定値 | AL．3L $\sim$ AL3H |  | $\begin{aligned} & \operatorname{Cod} 2 \text { 的R值 } \\ & >1 \text { 晾 } \end{aligned}$ |
| RL 3 L | 警報3下限設定値 | －1999～＋9999（E．U．） | －1999 |  |
| RL 3 H | 警報3上限設定値 |  | 9999 |  |
| HRIL 3 | AL3運澚 | 1 ～9999（E．U．） | 1 |  |
| $55^{\text {¢ }}$ P | 返啟動輸出值 | －100～100\％ | 0 |  |
| $55 \%$ | 返啟鲑時間 | OFF，0．01～8．00（時間，分） | OFF |  |
| $55 \%$ | 輸入值下限 | －1999～ 9999 | －1999 | 僅限定於線性翰入顳型 |
| F5c | 䤅入值上限 | －1999～9999 | 9999 |  |


| $d P$ | 小㖪點位置 | $\begin{aligned} & 0 \sim 3(\text { 線性輸入) } \\ & 0 \sim 1 \text { 其他輸入) } \end{aligned}$ | 0 |  |
| :---: | :---: | :---: | :---: | :---: |
| Fit | 輸入憈波常數 | 0 （關閉），0．1～20．0秒 | 1.0 |  |
| $104 \%$ | I／O 4 功能 | $\mathrm{ON}=$ 倀送器電源 OUT4 $=$ SSR輸出 Di2C＝DI接點 Di2U $=24 \mathrm{VDC}$ DI | OUT4 |  |
| d．f． 1 | DI 1 功能 | OFF， $1 \sim 21$ | OFF | DI1，DI2功能表 （參考下表） |
| d f．F． 2 | DI 2 功能 | OFF，1～21 | OFF |  |
| d 4 | DI動作選擇 | $\begin{aligned} & 0=\mathrm{DI} 1 \text { 正動作, } \mathrm{DI} 2 \text { 正動作 } \\ & 1=\mathrm{D} 11 \text { 屰動作, DI2正動作 } \\ & 2=\text { DI1正動作, DI2逆動作 } \\ & 3=\text { DI逆動作, DI逆動作 } \end{aligned}$ | 0 | 僅在配置DI2時使用 |
| u5rb | ［［8］功能選擇 | nonE，tunE，oplo，aac，asi，chsp， st．by，str．t | tunE | （ 功能表 <br> （参照下表） |
| d 4.6 | 輸入值䫫示顔色切換 | $\begin{aligned} & 0=\text { 自動切換 } \\ & 1=\text { 紅色 } \\ & 2=\text { 綠色 } \\ & 3=\text { 掃色 } \end{aligned}$ | 2 | 設宣為＂自剅切撸＂時，嘗PV在 AdE到SP的箟国內 |
| RdE |  | 0（關閉）～9999（E．U．） |  | 高於AdE誩営飆紅色，如柰PV低於 AdE則買爱管色： |
| $\square^{\square} 5.2$ | 電源自動關閉時間 | OFF（不關閉電源） $0.1 \sim 99.59$（ | OFF |  |
| Rdd | 通訊機號 | $1 \sim 254$ | 1 | Modbus RTU通訊協定 |
| bRud | 通訊速率 | 1200，2400，9600，19200，38400 | 9600 |  |
| Uoit | 負載電厴 | $1 \sim 999$（V） | 230 | Code 的S值$>1 \text { 時 }$ |
| гur | 負載電流 | $1 \sim 9999$（A） |  |  |
| PR54 | 硬體參數層密碼設置 | 201～400 | 300 |  |
| PR52 | 參數層密碼設置 | OFF（0），1～200 | 20 |  |

diF i d，F己 DI1，DI2 功能表

| 顯示代碼 | 内容 |
| :---: | :---: |
| 0 | 關閉（初始值） |
| 1 | 重音警報 |
| 2 | 警報楕認（ACK） |
| 3 | 翰入值保持 |
| 4 | 待機模式 |
| 5 | 手動模式 |
| 6 | 「SP」加熱，「SP2」冷卻 |
| $7 \sim 17$ | 備用 |
| 18 | 選擇設定點順序［轉換時］ |
| 19 | SP／SP2選擇 |
| 20 | $\begin{aligned} & \text { SP二進制代碼切換 (DI1, DI2使用) } \\ & (0=S P, ~ 01=S 2, ~ 10=S P 3, ~ 11=S P 4) \end{aligned}$ |
| 21 | 數字翰入 與［ 向上鍵］和［向下鍵］並行 （DI1＝「向上 」 鉻 ，DI2＝「向下」 鍏） |

## L5rb 回 功能表

| 顯示代碼 | 内容 |
| :---: | :---: |
| nanE | 未使用 |
| tunE | 啟動自動演算（初始值） |
| $\square \square_{\text {PL }}$ | 自動／手動切換 |
| RR ${ }_{\text {c }}$ | 重囬警報 |
| R5， | 警報碳認 |
| ch5P | 目標設定點選擇（顯示SP，SP2，SP3） |
| 5t．a3 | 待機模式 |

（四）其他：


## Appendix A

## ${ }^{-1}$ inP GROUP - Main and auxiliary input configuration

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | SEnS | Sensor selection | 0 | $\begin{aligned} & \hline \mathrm{J}=\mathrm{TC} \mathrm{~J}, \\ & \mathrm{CrAL}=\mathrm{T}, \mathrm{~K}, \\ & \mathrm{~S}=\mathrm{TC} \mathrm{~S}, \\ & \mathrm{r}=\mathrm{TC} R, \\ & \mathrm{t}=\mathrm{TC}, \mathrm{~T}, \\ & \mathrm{Pt1}=\mathrm{RTD} \mathrm{Pt100}, \\ & \mathrm{P} 10=\mathrm{RTD} \mathrm{Pt1000}, \\ & 0.60=0 \text { to } 60 \mathrm{mV}, \\ & 12.60=12 \text { to } 60 \mathrm{mV}, \\ & 0.20=00 \text { t } 20 \mathrm{~mA}, \\ & 4.20=4 \text { to } 20 \mathrm{~mA}, \\ & 0.5=0 \text { to } 5 \mathrm{~V}, \\ & 1.5=1 \text { to } 5 \mathrm{~V}, \\ & 0.10=0 \text { to } 10 \mathrm{~V}, \\ & 2.10=2 \text { to } 10 \mathrm{~V} \\ & \hline \end{aligned}$ | $J$ |
| 2 | dp | Decimal Point Position (linear inputs) | 0 | 0 to 3 | 0 |
|  |  | Decimal Point Position (different than linear inputs) |  | 0/1 |  |
| 3 | SSC | Initial scale read-out for linear inputs | dp | -1999 to 9999 | 0 |
| 4 | FSc | Full Scale Readout for linear inputs | dp | -1999 to 9999 | 1000 |
| 5 | unit | Engineer unit |  | ${ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ | ${ }^{\circ} \mathrm{C}$ |
| 6 | Fil | Digital filter on the measured value | 1 | 0 (= OFF) to 20.0 s | 1.0 |
| 7 | inE | Sensor error used to enable the safety output value |  | $\begin{aligned} & \text { or = Over range } \\ & \text { ou = Under range } \\ & \text { our = Over and under range } \\ & \hline \end{aligned}$ | our |
| 8 | oPE | Safety output value (\% of the output) |  | -100 to 100 | 0 |
| 9 | IO4.F | I/O 4 function |  | on $=$ Output used as PWS for TX, <br> out4 $=$ Output 4 (digital output 4$),$ <br> dG2c $=$ Digital input 2 driven by contact, <br> dG2U $=$ Digital input 2 driven by voltage | out4 |
| 10 | diF1 | Digital Input 1 function |  | $\begin{aligned} & \text { oFF = Not used, } \\ & 1=\text { Alarm reset, } \\ & 2=\text { Alarm acknowledge (ACK), } \\ & 3=\text { Hold of the measured value, } \\ & 4=\text { Stand by mode, } \\ & 5 \text { = Manual mode, } \end{aligned}$ | oFF |
| 11 | diF2 | Digital Input 2 function |  | $6=$ HEAt with SP1 and CooL with SP2, <br> 7 to $17=$ No action <br> 18 = Sequential SP selection, <br> 19 = SP1 - SP2 selection, <br> $20=$ SP1 to SP4 binary selection, <br> 21 = Digital inputs in parallel to <br> and <br> keys | oFF |
| 12 | di.A | Digital Inputs Action (DI2 only if configured) |  | $\begin{aligned} & 0=\text { DI1 direct action, DI2 direct action } \\ & 1=\text { DI1 reverse action, DI2 direct action } \\ & 2=\text { DI1 direct action, D12 reverse action } \\ & 3=\text { DI1 reverse action, DI2 reverse action } \end{aligned}$ | 0 |

${ }^{7}$ Out group

| no. | Param. | Description | Dec. <br> Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 13 | 01t | Output 1 type (when Out 1 is an analog output) |  | $0-20=0$ to $20 \mathrm{~mA} ;$ $4-20=$ 4 to $20 \mathrm{~mA} ;$ $0-10=$ $2-10=$ 2 to $10 \mathrm{~V} ;$ | 0-20 |
|  |  | Out 1 function (when Out 1 is an analog output) | 0 | NonE = Output not used; <br> H.rEG = Heating output; <br> c.rEG = Cooling output; <br> r.inP = Measure retransmission; <br> r.Err = Error (SP - PV) retransmission; <br> r.SP = Set point retransmission ; <br> r.SEr = Serial value retransmission. |  |
| 14 | 01F | Out 1 function | 0 | ```NonE = Output not used H.rEG = Heating output c.rEG \(=\) Cooling output AL = Alarm output t.out \(=\) Reserved t.HoF = Reserved P.End = Reserved P.HLd = Reserved P.uit \(=\) Reserved P.run = Reserved P.Et1 = Reserved P.Et2 \(=\) Reserved or.bo \(=\) Out-of-range or burn out indicator P.FAL \(=\) Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator St.bY = Stand by status indicator diF. 1 = The output repeats the digital input 1 status diF. \(2=\) The output repeats the digital input 2 status on \(=\) Out 1 always \(O N\) riSP = Inspection requested (the worked hours/days counter has reached the programmed threshold)``` | H.rEG |
| 15 | Ao1L | Initial scale value of the analog retransmission (when Out 1 is an analog output) | dP | -1999 ... Ao1H | -1999 |
| 16 | Ao1H | Full scale value of the analog retransmission (when Out 1 is an analog output) | dP | Ao1L ... 9999. | 9999 |
| 17 | 01AL | Alarms linked up with the out 1 | 0 | 0 to 63  <br> $+1=$ Alarm 1 <br> $+2=$ Alarm 2 <br> $+4=$ Alarm 3 <br> $+8=$ Loop break alarm <br> $+16=$ Sensor Break <br> $+32=$ Overload on output 4 | AL1 |
| 18 | 01Ac | Out 1 action | 0 | dir $=$ Direct action <br> $\mathrm{rEU}=$ Reverse action <br> dir. $=$ Direct with reversed LED <br> ReU. $\mathrm{r}=$ Reverse with reversed LED | dir |
| 19 | 02F | Out 2 function | 0 | ```NonE = Output not used H.rEG = Heating output c.rEG \(=\) Cooling output AL \(=\) Alarm output t.out \(=\) Reserved t. \(\mathrm{HoF}=\) Reserved P.End \(=\) Reserved P.HLd = Reserved P.uit \(=\) Reserved P.run \(=\) Reserved P.Et1 \(=\) Reserved P.Et2 \(=\) Reserved or.bo \(=\) Out-of-range or burn out indicator P.FAL \(=\) Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator St.bY = Stand by status indicator diF. \(1=\) The output repeats the digital input 1 status diF. \(2=\) The output repeats the digital input 2 status on = Out 2 always ON riSP = Inspection requested (the worked hours/days counter has reached the programmed threshold)``` | AL |
| 20 | 02AL | Alarms linked up with the out 2 | 0 | 0 to 63  <br> $+1=$ Alarm 1 <br> $+2=$ Alarm 2 <br> $+4=$ Alarm 3 <br> $+8=$ Loop break alarm <br> $+16=$ Sensor Break <br> $+32=$ Overload on output 4 | AL1 |


| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 21 | o2Ac | Out 2 action | 0 | dir $=$ Direct action <br> $\mathrm{rEU}=$ Reverse action <br> dir. $\mathrm{r}=$ Direct with reversed LED <br> ReU. $\mathrm{r}=$ Reverse with reversed LED | dir |
| 22 | o3F | Out 3 function | 0 | ```NonE = Output not used H.rEG \(=\) Heating output c.rEG \(=\) Cooling output AL = Alarm output t.out = Reserved t.HoF = Reserved P.End \(=\) Reserved P.HLd = Reserved P.uit \(=\) Reserved P.run = Reserved P.Et1 \(=\) Reserved P.Et2 \(=\) Reserved or.bo \(=\) Out-of-range or burn out indicator P.FAL = Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator St.bY = Stand by status indicator diF. \(1=\) The output repeats the digital input 1 status diF. \(2=\) The output repeats the digital input 2 status on \(=\quad\) Out 3 always ON riSP = Inspection requested (the worked hours/days counter has reached the programmed threshold)``` | AL |
| 23 | -3AL | Alarms linked up with the out 3 | 0 | 0 to 63  <br> $+1=$ Alarm 1 <br> $+2=$ Alarm 2 <br> $+4=$ Alarm 3 <br> $+8=$ Loop break alarm <br> $+16=$ Sensor Break <br> $+32=$ Overload on output 4 | AL2 |
| 24 | o3Ac | Out 3 action | 0 | dir $=$ Direct action <br> $\mathrm{rEU}=$ Reverse action <br> dir. $\mathrm{r}=$ Direct with reversed LED <br> ReU. $\mathrm{r}=$ Reverse with reversed LED | dir |
| 25 | 04F | Out 4 function | 0 | ```NonE = Output not used H.rEG = Heating output c.rEG \(=\) Cooling output \(\mathrm{AL}=\quad\) Alarm output t.out \(=\) Reserved t.HoF = Reserved P.End \(=\) Reserved P.HLd = Reserved P.uit \(=\) Reserved P.run = Reserved P.Et1 \(=\) Reserved P.Et2 \(=\) Reserved or.bo \(=\) Out-of-range or burn out indicator P.FAL = Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator St.bY = Stand by status indicator``` | AL |
| 26 | 04AL | Alarms linked up with the out 4 | 0 | 0 to 63  <br> $+1=$ Alarm 1 <br> $+2=$ Alarm 2 <br> $+4=$ Alarm 3 <br> $+8=$ Loop break alarm <br> $+16=$ Sensor Break <br> $+32=$ Overload on output 4 | $\begin{aligned} & \text { AL1 + } \\ & \text { AL2 } \end{aligned}$ |
| 27 | 04Ac | Out 4 action | 0 | dir $=$ Direct action <br> $r E U=$ Reverse action <br> dir. $r=$ Direct with reversed LED <br> ReU. $r=$ Reverse with reversed LED | dir |

${ }^{7}$ AL1 group

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 28 | AL1t | Alarm 1 type | 0 | nonE = Alarm not used <br> LoAb $=$ Absolute low alarm <br> $\mathrm{HiAb}=$ Absolute high alarm <br> LHAo = Windows alarm in alarm outside the windows <br> LHAI = Windows alarm in alarm inside the windows <br> SE.br = Sensor Break <br> LodE = Deviation low alarm (relative) <br> HidE $=$ Deviation high alarm (relative) <br> LHdo $=$ Relative band alarm in alarm out of the band <br> LHdi $=$ Relative band alarm in alarm inside the band | HiAb |
| 29 | Ab1 | Alarm 1 function | 0 | ```0 to 15 \(+1=\) Not active at power up \(+2=\) Latched alarm (manual reset) +4 = Acknowledgeable alarm \(+8=\) Relative alarm not active at set point change``` | 0 |
| 30 | AL1L | - For High and low alarms, it is the low limit of the AL1 threshold; <br> - For band alarm, it is low alarm threshold | dp | From -1999 to AL1H (E.U.) | -1999 |
| 31 | AL1H | - For High and low alarms, it is the high limit of the AL1 threshold; <br> - For band alarm, it is high alarm threshold | dp | From AL1L to 9999 (E.U.) | 9999 |
| 32 | AL1 | AL1 threshold | dp | From AL1L to AL1H (E.U.) | 0 |
| 33 | HAL1 | AL1 hysteresis | dp | 1 to 9999 (E.U.) | 1 |
| 34 | AL1d | AL1 delay | 0 | From 0 (oFF) to 9999 (s) | oFF |
| 35 | AL1o | Alarm 1 enabling during Stand-by mode and out of range conditions | 0 | $0=$ Alarm 1 disabled during Stand by and out of range <br> $1=$ Alarm 1 enabled in stand by mode <br> $2=$ Alarm 1 enabled in out of range condition <br> $3=$ Alarm 1 enabled in stand by mode and in overrange condition | 0 |

## "AL2 group

| no. | Param. | Description | $\begin{array}{l}\text { Dec. } \\ \text { Point }\end{array}$ |  | Values |
| :--- | :--- | :--- | :--- | :--- | :--- |$]$| Default |
| :--- |
| 36 |
| AL2t |
| Alarm 2 type |

${ }^{3}$ AL3 group

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 44 | AL3t | Alarm 3 type | 0 | nonE $=$ Alarm not used LoAb $=$ Absolute low alarm $\mathrm{HiAb}=$ Absolute high alarm $\mathrm{LHAo}=$ Windows alarm in alarm outside the windows LHAI $=$ Windows alarm in alarm inside the windows $\mathrm{SE} \cdot \mathrm{br}=$ Sensor Break LodE $=$ Deviation low alarm (relative) HidE $=$ Deviation high alarm (relative) LHdo $=$ Relative band alarm in alarm out of the band LHdi $=$ Relative band alarm in alarm inside the band | nonE |
| 45 | Ab3 | Alarm 3 function | 0 | $\begin{aligned} & 0 \text { to } 15 \\ & +1=\text { Not active at power up } \\ & +2=\text { Latched alarm (manual reset) } \\ & +4=\text { Acknowledgeable alarm } \\ & +8=\text { Relative alarm not active at set point change } \\ & \hline \end{aligned}$ | 0 |
| 46 | AL3L | - For High and low alarms, it is the low limit of the AL3 threshold; <br> - For band alarm, it is low alarm threshold | dp | From -1999 to AL3H (E.U.) | -1999 |
| 47 | AL3H | - For High and low alarms, it is the high limit of the AL3 threshold; <br> - For band alarm, it is high alarm threshold | dp | From AL3L to 9999 (E.U.) | 9999 |
| 48 | AL3 | AL3 threshold | dp | From AL3L to AL3H (E.U.) | 0 |
| 49 | HAL3 | AL3 hysteresis | dp | 1 to 9999 (E.U.) | 1 |
| 50 | AL3d | AL3 delay | 0 | From 0 (oFF) to 9999 (s) | oFF |
| 51 | AL3o | Alarm 3 enabling during Stand-by mode and out of range conditions | 0 | $0=$ Alarm 3 disabled during Stand by and out of range <br> $1=$ Alarm 3 enabled in stand by mode <br> $2=$ Alarm 3 enabled in out of range condition <br> 3 = Alarm 3 enabled in stand by mode and in overrange condition | 0 |

## ${ }^{7}$ LBA group - Loop Break Alarm Parameters

| no. | Param. | Description | Dec. <br> Point | Values | Default |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 52 | LbAt | LBA time | 0 | From 0 (oFF) to 9999 (s) | oFF |
| 53 | LbSt | Delta measure used by LBA during Soft start | dP | From 0 (oFF) to 9999 (E.U.) | 10 |
| 54 | LbAS | Delta measure used by LBA | dP | 1 to 9999 (E.U.) | 20 |
| 55 | LbcA | Condition for LBA enabling | 0 | uP $\quad$Active when Pout $=100 \%$ <br> dn <br> Active when Pout $=-100 \%$ <br> both $=$ Active in both cases | both |

## ${ }^{7}$ rEG group - Control Parameters

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 56 | cont | Control type | 0 | Pid $=$ PID (heat and/or) <br> On.FA $=$ ON/OFF asymmetric hysteresis  <br> On.FS $=$ ON/OFF symmetric hysteresis <br> $\mathrm{nr}=$ Heat/Cool ON/OFF control with neutral zone | Pid |
| 57 | Auto | Autotuning selection | 0 | $-4=$ Oscillating auto-tune with automaticrestart at power up and after all point change <br> $-3=$ Oscillating auto-tune with manual start <br> $-2=$ Oscillating -tune with auto-matic start at the first power up only <br> $-1=$ Oscillating auto-tune with auto-matic restart at every power up <br> $0=$ Not used <br> 1 = Fast auto tuning with automatic restart at every power up <br> $2=$ Fast auto-tune with automatic start the first power up only <br> $3=$ FAST auto-tune with manual start <br> $4=$ FAST auto-tune with automatic restart at power up and after a set point change <br> 5 = Evo-tune with automatic restart at every power up <br> $6=$ Evo-tune with automatic start the first power up only <br> 7 = Evo-tune with manual start <br> $8=$ Evo-tune with automatic restart at power up and after a set point change | 7 |
| 58 | Aut.r | Manual start of the Autotuning | 0 | oFF $=$ Not active <br> on $=$ Active | oFF |


| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 59 | SELF | Self tuning enabling | 0 | no $=\quad$ The instrument does not perform the self-tuning <br> YES $=$ The instrument is performing the self-tuning | no |
| 60 | HSEt | Hysteresis of the ON/OFF control | dP | 0 to 9999 (E.U.) | 1 |
| 61 | cPdt | Time for compressor protection | 0 | From 0 (oFF) to 9999 (s) | oFF |
| 62 | Pb | Proportional band | dP | 1 to 9999 (E.U.) | 50 |
| 63 | ti | Integral time | 0 | From 0 (oFF) to 9999 (s) | 200 |
| 64 | td | Derivative time | 0 | From 0 (oFF) to 9999 (s) | 50 |
| 65 | Fuoc | Fuzzy overshoot control | 2 | 0.00 to 2.00 | 0.50 |
| 66 | tch | Heating output cycle time | 1 | 0.1 to 130.0 (s) | 20.0 |
| 67 | rcG | Power ratio between heating and cooling action | 2 | 0.01 to 99.99 | 1.00 |
| 68 | tcc | Cooling output cycle time | 1 | 0.1 to 130.0 (s) | 20.0 |
| 69 | rS | Manual reset (Integral pre-load) | 1 | -100.0 to +100.0 (\%) | 0.0 |
| 70 | Str.t | Servomotor stroke time | 0 | 5 to 1000 seconds | 60 |
| 71 | db.S | Servomotor dead band | 0 | 0 to 100\% | 50 |
| 72 | od | Delay at power up | 2 | From 0.00 (oFF) to 99.59 (hh.mm) | oFF |
| 73 | St.P | Maximum power output used during soft start | 0 | -100 to 100 (\%) | 0 |
| 74 | SSt | Soft start time | 2 | $\begin{array}{\|ll} \hline- & 0.00 \text { (oFF); } \\ - & 0.01 \text { to } 7.59 \text { (hh.mm); } \\ - & \text { inF (always ON). } \\ \hline \end{array}$ | oFF |
| 75 | SS.tH | Threshold for soft start disabling | dP | -1999 to +9999 (E.U.) | 9999 |

## ${ }^{-}$SP group - Set point parameters

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 76 | nSP | Number of used set points | 0 | 1 to 4 | 1 |
| 77 | SPLL | Minimum set point value | dP | From -1999 to SPHL | -1999 |
| 78 | SPHL | Maximum set point value | dP | From SPLL to 9999 | 9999 |
| 79 | SP | Set point 1 | dP | From SPLL to SPLH | 0 |
| 80 | SP 2 | Set point 2 | dP | From SPLL to SPLH | 0 |
| 81 | SP 3 | Set point 3 | dP | From SPLL to SPLH | 0 |
| 82 | SP 4 | Set point 4 | dP | From SPLL to SPLH | 0 |
| 83 | A.SP | Selection of the active set point | 0 | From 1 (SP 1) to nSP | 1 |
| 84 | SP.rt | Remote set point type | 0 | RSP = The value coming from serial link is used as remote set point; <br> trin $=\quad$ The value will be added to the local set point selected by A.SP and the sum becomes the operative set point; <br> PErc $=$ The value will be scaled on the input range and this value will be used as remote SP. | trin |
| 85 | SPLr | Local/remote set point selection | 0 | Loc = local; <br> $\mathrm{rEn}=$ remote. | Loc |
| 86 | SP.u | Rate of rise for POSITIVE set point change (ramp UP) | 2 | 0.01 to 99.99 (inF) Eng. units per minute | inF |
| 87 | SP.d | Rate of rise for NEGATIVE set point change (ramp DOWN) | 2 | 0.01 to 99.99 (inF) Eng. units per minute | inF |

## 'PAn group - Operator HMI parameters

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 118 | PAS2 | Level 2 password (limited access level) | 0 | - oFF (Level 2 not protected by password); <br> - 1 to 200. | 20 |
| 119 | PAS3 | Level 3 password (complete configuration level) | 0 | 3 to 200 | 30 |
| 120 | PAS4 | Level 4 password (CODE configuration level) | 0 | 201 to 400 | 300 |
| 121 | uSrb | © button function during RUN TIME |  | ```nonE = No function; tunE \(=\) Auto-tune/self-tune enabling. A single press (longer than 1 se- cond) starts the auto-tune; oPLo = Manual mode. The first pressure puts the instrument in manual mode (OPLO) while a second one puts the instrument in Auto mode; AAc = Alarm reset; \(\mathrm{ASi}=\quad\) Alarm acknowledge; chSP = Sequential set point selection; St.by = Stand by mode. The first press puts the instrument in stand by mode while a second one puts the instrument in Auto mode; Str.t = Reserved; P.run \(=\) Reserved; P.rES = Reserved; P.r.H.r = Reserved.``` | tunE |
| 122 | diSP | Display management |  | nonE $=$ Standard display; <br> Pou $=$ Power output; <br> SPF $=$ Final set point; <br> Spo $=$ Operative set point; <br> AL1 $=$ Alarm 1 threshold; <br> AL2 $=$ Alarm 2 threshold; <br> AL3 $=$ Alarm 3 threshold; <br> Pr.tu $=$ Reserved; <br> Pr.td $=$ Reserved; <br> P.t.tu $=$ Reserved; <br> P.t.td $=$ Reserved; <br> ti.uP $=$ Reserved; <br> tid.du $=$ Reserved; <br> PErc $=$ Percent of the power output used during soft start (when the soft <br>  start time is equal to infinite, the limit is ever active and it can be <br>  used also when ON/OFF control is selected). | 0 |
| 123 | di.cL | Display colour |  | $\begin{aligned} & 0=\text { The display colour is used to show the actual deviation (PV - SP); } \\ & 1=\text { Display red (fix); } \\ & 2=\text { Display green (fix); } \\ & 3=\text { Display orange (fix). } \end{aligned}$ | 0 |
| 124 | AdE | Deviation for display colour management |  | 1 to 999 (E.U.) | 5 |
| 125 | di.St | Display Timeout | 2 | - oFF (display always ON); <br> - 0.1 to 99.59 (mm.ss). | oFF |
| 126 | fild | Filter on the displayed value | 1 | - oFF (filter disabled) <br> - From 0.0 (oFF) to 20.0 (E.U.) | oFF |
| 128 | dSPu | Instrument status at power ON |  | ```AS.Pr = Starts in the same way it was prior to the power down; Auto = Starts in Auto mode; oP.0 = Starts in manual mode with a power output equal to zero; St.bY = Starts in stand-by mode.``` | AS.Pr |
| 129 | oPr.E | Operative modes enabling |  | ALL = All modes will be selectable by the next parameter; <br> Au.oP = Auto and manual (OPLO) mode only will be selectable by the next parameter; <br> $\mathrm{Au} . \mathrm{Sb}=$ Auto and Stand-by modes only will be selectable by the next parameter. | ALL |
| 130 | oPEr | Operative mode selection |  |  | Auto |

${ }^{7}$ Ser group - Serial link parameters

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 131 | Add | Instrument address |  | - oFF <br> - 1 to 254 | 1 |
| 132 | bAud | baud rate |  | $1200=1200$ baud $2400=2400$ baud $9600=9600$ baud $19.2=19200$ baud $38.4=38400$ baud | 9600 |
| 133 | trSP | Selection of the value to be retransmitted (Master) |  | nonE $=$Retransmission not used (the instrument is a slave); <br> $\mathrm{rSP}=$ <br> The instrument becomes a Master and retransmits the operati- <br> ve set point;PErc $=$The instrument become a Master and it retransmits the power <br> output. | nonE |

## ${ }^{7}$ COn group - Consumption parameters

| no. | Param. | Description | Dec. Point | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 134 | Co.tY | Count type |  | oFF = Not used; <br> 1 = Instantaneous power (kW); <br> $2=$ Power consumption (kW/h); <br> 3 = Reserved; <br> $4=$ Total worked days: number of hours the instrument is turned ON divided by 24; <br> $5=$ Total worked hours: number of hours the instrument is turned ON; <br> $6=$ Total worked days with threshold: number of hours the instrument is turned ON divided by 24, the controller is forced in standby when Co.ty value reaches the threshold set in [137] h.Job; <br> $7=$ Total worked hours with threshold: number of hours the instrument is turned ON, the controller is forced in stand-by when Co.ty value reaches the threshold set in [137] h.Job; <br> $8=$ Totalizer of control relay worked days: number of hours the control relay has been in ON condition, divided by 24; <br> $9=$ Totalizer of control relay worked hours: number of hours the control relay has been in ON condition; <br> $10=$ Totalizer of control relay worked days with threshold: number of hours the control relay has been in ON condition divided by 24 , the controller is forced in stand-by when Co.ty value reaches the threshold set in [137] h.Job; <br> $11=$ Totalizer of control relay worked hours with threshold: number of hours the control relay has been in ON condition, the controller is forced in stand-by when Co.ty value reaches the threshold set in [137] h.Job. | oFF |
| 135 | UoLt | Nominal Voltage of the load |  | 1 to 9999 (V) | 230 |
| 136 | cur | Nominal current of the load |  | 1 to 999 (A) | 10 |
| 137 | h.Job | Threshold of the working period |  | $\begin{array}{\|l} \hline \text { oFF }=\text { threshold not used } \\ 0 \text { to } 9999 \text { days }(\text { when }[133] \cot Y=4) \\ 0 \text { to } 9999 \text { hours (when }[133] \cot Y=5) \\ \hline \end{array}$ | 0 |
| 138 | t.Job | Worked time (not resettable) |  | 0 to 9999 days |  |

## ${ }^{7}$ CAI group - User calibration parameters

| no. | Param. | Description | Dec. <br> Point | Values | Default |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 139 | AL.P | Adjust Low Point |  | From -1999 to (AH.P -10$)$ in engineering units | 0 |
| 140 | AL.o | Adjust Low Offset |  | -300 to $+300($ E.U. $)$ | 0 |
| 141 | AH.P | Adjust High Point |  | From (AL.P +10$)$ to 9999 engineering units | 9999 |
| 142 | AH.o | Adjust High Offset |  | -300 to +300 | 0 |

